

G6 Markrobotter for økologer, lugerobotter

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Special konsulent SEGES Økologi Innovation

SEGES



Hvad er der og hvad kan de

Lugerobotter:

Steketee

Garford robocrop

Poulsen robovator

Redskabsbærere:

Robotti mm.



Steketee

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- Soil cultivation
- Mechanical weeding
 - Hoeing elements
 - Bearers
 - Front Hoeing Machine
 - Cultivation Tine Weeder
 - Disc Hoeing Machine
 - Finger weeder
 - **Steketee IC**
 - Torsion weeder
 - Steketee IC-Light auto...
 - Hoeing blades
- Chemical weeding
- Bed formers
- Storage and Keeping
- Front Linkage Device
- Rollers

Steketee IC

[Technical specification](#)

The IC is Steketee's automatic hoeing machine that uses camera images to hoe around the plants accurately and quickly.

The IC is Steketee's automatic hoeing machine that uses camera images to calculate the positions of cultivated crops and is able to hoe around them accurately and quickly. The IC is able to hoe all green crops that are planted in a row. For other crops, such as red lettuce, we are able to supply extension programmes.

In order to provide accurate quality inter-row and inter-plant cultivations a wide variety of hoeing blades and tines are available such as cultivating tines, torsion weeders, finger weeders, harrow weeders, etc. In addition, it is possible to apply row spraying or even crop specific spraying.

As an added benefit the digital recordings made whilst hoeing can be utilized to count the crops, measure the green surface of the crops or establish the discolouration of the crops.



Garford Robocrop

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RU Для просмотра этой страницы на русском языке

garford
providing advanced technology for progressive farming

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Robocrop InRow Weeder






The Garford Robocrop InRow Weeder uses tried and tested Robocrop video image analysis techniques to locate individual plants in order to mechanically remove weeds from the inter row and importantly within the crop row between the plants.

Developed for use on transplanted crops such as lettuce, cabbage, celery etc Robocrop InRow can however be used on most crops that are planted with regular plant and row spacing where the plant foliage is clearly separated from the next plant.

Forward speeds of up to 3 plant spacings per second are possible. Systems of up to 18 rows and 6mtr working width can be supplied.

Click to view a PDF of the Robocrop InRow Weeder brochure.
This will open in a new browser window.

Move the mouse over these thumbnail images for an enlarged image.

 <p>Robocrop InRow Weeder 20 row eRotor</p>	 <p>Robocrop InRow 9 row triple split</p>
 <p>Robocrop InRow 15 row bunched onions</p>	 <p>Robocrop InRow Lettuce 01</p>
 <p>Robocrop InRow lettuce 02</p>	 <p>Robocrop InRow rotor lettuce</p>
 <p>Robocrop InRow tracking image</p>	 <p>Robocrop InRow triple bed split in brassicas</p>

<https://vimeo.com/172547817>

Kræver plantede roer, de er ikke med i projektet

Frank Poulsen



- an engineering company specializing in advanced technical solutions

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We are developing and manufacturing robots for organic and conventional farming, providing efficient and economical weed control without the use of herbicides.



<http://www.visionweeding.com/videos/>

Arbejder med udvikling af berøringsfri teknologi og nye sensorprogrammering med ukrudts genkendelse. Ved ikke hvornår det bliver operationelt til roer.

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